## HOVERMAP ST AND ST-X

HARDWARE FEATURES AND DATA CAPTURE

## HOVERMAP HARDWARE FEATURES

IOVERMA	PHARDWARE FEATURES	MAPPING	PLUS	AUTONOM
\$ 	Versatile Hardware Scan locations without GPS by walking, driving or flying with the same hardware.	$\checkmark$	$\checkmark$	$\checkmark$
(((r· 0	No GPS Required Map any environment quickly and safely with Hovermap's SLAM localization.	$\checkmark$	$\checkmark$	$\checkmark$
00	IP65 Rating IP65 rated unit is protected against dust and low-pressure jets of water from all directions, making it ideal for use in harsh environments.	$\checkmark$	$\checkmark$	$\checkmark$
Å	<b>Obstacle Proximity Map*</b> Use the proximity map to avoid obstacles and navigate the drone safely from a distance.		$\checkmark$	$\checkmark$
0	Accessory Port An accessory port and mount points expand Hovermap ST's capability with accessories such as a long-range radio.	$\checkmark$	$\checkmark$	$\checkmark$
	Drone Mountable <sup>★</sup> Attach the Hovermap payload to a compatible drone to use it as an all-in-one 3D mapping device.	$\checkmark$	$\checkmark$	$\checkmark$
	Smart Battery Return-to-Home Maximize flight time and return the drone to base safely using Hovermap's battery monitoring and shortest route home features.		$\checkmark$	$\checkmark$
<b>(5)</b>	Magnetic Interference Tolerance Maintain flight stability in areas of magnetic interference.		$\checkmark$	$\checkmark$
PC	Barometric pressure Fly safely in tight spaces where air pressure fluctuates using the Hovermap SLAM altitude control feature.		$\checkmark$	$\checkmark$
IOVERMA	P DATA CAPTURE	MAPPING	PLUS	AUTONON
$\bigcirc$	GPS Denied Flight* Allows drones to fly autonomously in GPS-denied environments, enabling a host of new applications such as flying and mapping in underground mines, inside warehouses or inspecting underneath bridges.		$\checkmark$	$\checkmark$
	Omnidirectional Collision Avoidance Create a virtual safety shield around the drone and avoid the smallest of obstacles.		$\checkmark$	$\checkmark$
((( ↑↓ >)))	Real-Time Point Cloud Streaming View the 3D point cloud of your mapped environment in real time.	$\checkmark$	$\checkmark$	$\checkmark$
ిర్య	Smart Waypoints Let the drone self-navigate to pre-set waypoints and monitor its progress via a live-streamed 3D map.			~
<u>ه</u>	Beyond Line-Of Sight Flight (BLOS) Capture complex assets with a BVLOS Hovermap flight in GPS-denied environments.			$\checkmark$
	Outland Fundamentian and Intelligent Dath Diamains			
L L	Guided Exploration and Intelligent Path Planning Hovermap's autonomous path planning algorithms guide the drone through its flight mission.			$\checkmark$
<u>ک</u>				
	Hovermap's autonomous path planning algorithms guide the drone through its flight mission. Tap-To-Fly Operation			
	Hovermap's autonomous path planning algorithms guide the drone through its flight mission. <b>Tap-To-Fly Operation</b> Fly an entire mission, from take-off to landing, with Hovermap's easy to use interface. <b>Communication Loss Return-To-Home</b>			✓ ✓ ✓ ✓
	Hovermap's autonomous path planning algorithms guide the drone through its flight mission.         Tap-To-Fly Operation         Fly an entire mission, from take-off to landing, with Hovermap's easy to use interface.         Communication Loss Return-To-Home         Minimize the risk from communications loss between the drone and Hovermap.         Live Stream Onboard Drone Camera*			
	Hovermap's autonomous path planning algorithms guide the drone through its flight mission. <b>Tap-To-Fly Operation</b> Fly an entire mission, from take-off to landing, with Hovermap's easy to use interface. <b>Communication Loss Return-To-Home</b> Minimize the risk from communications loss between the drone and Hovermap. <b>Live Stream Onboard Drone Camera*</b> View a live stream of the mission with an integrated drone camera and Emesent software. <b>Operate Beyond Communication Range</b>	✓		

\*Requires additional hardware to enable features

## AURA

## INTEGRATED PROCESSING AND VISUALIZATION SOFTWARE INCLUDED WITH ALL SUBSCRIPTIONS

AURA LITE		MAPPING	PLUS	AUTONOMY
	A single streamlined application workflow Process and visualize your data in one intuitive platform.	$\checkmark$	$\checkmark$	~
Ş	Multi-frame rendering Proprietary visualization algorithms enable seamless manipulation of large point clouds. Visualize your point cloud in the highest detail, providing deeper insights.	$\checkmark$	$\checkmark$	~
	Reliable high-quality processing Processing powered by the worlds leading SLAM algorithm, converting your data into highly, accurate point clouds.	$\checkmark$	$\checkmark$	~
	Export to a range of formats output in.LAZ, LAS, PLY & E57 Output the processed point cloud data to LAZ, LAS, PLY and E57 into your required file type.	$\checkmark$	$\checkmark$	$\checkmark$
	Clean Point Cloud Cleaning Tools Clean your point cloud at the touch of a button with SOR (Statistical Outlier Removal) and DBD (Decimate by Distance) filters.	$\checkmark$	$\checkmark$	$\checkmark$
$\mathbb{C}^{\mathbb{N}}_{\mathbb{A}}$	GPS Auto-Geolocation Automatically align scans automatically to GPS coordinates when Hovermap is mounted to a compatible drone.	$\checkmark$	$\checkmark$	$\checkmark$
Ŷ	<b>3D Tools for Improved Analysis</b> A range of 3D tools allows you to easily manipulate point clouds, reducing the risk or error and improving analysis.	$\checkmark$	$\checkmark$	~
AURA SOFT	WARE	MAPPING	PLUS	AUTONOMY
	Batch Processing Save time by queueing multiple jobs to process automatically in the background.	$\checkmark$	$\checkmark$	$\checkmark$
$\checkmark$	Automated Ground Control Point (GCPs)* Automated georeferencing and survey grade accuracy enhancement.	$\checkmark$	$\checkmark$	$\checkmark$
	Colorization* Enhance visualization and analysis by adding true colour to Hovermap point clouds.	$\checkmark$	$\checkmark$	$\checkmark$
Ê	Point Cloud Merging Combine multiple point clouds to produce a single seamless scan.	$\checkmark$	$\checkmark$	~
ś⊕	Personalised Processing Profiles Create customized profiles or reuse existing profiles to process scans with minimal configuration.	$\checkmark$	$\checkmark$	$\checkmark$

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